

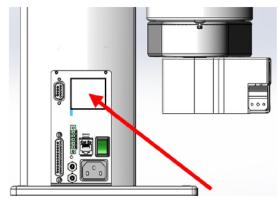
TSB-1314

-3101 Error, PreciseFlex 400 Revision D Robot

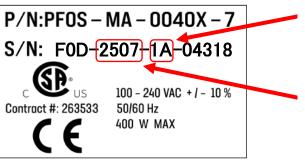
Rev A

Product(s) Affected:

PreciseFlex 400 robots with serial number label date range of 2507 – 2509 and serial label revision of 1A.



Product Label at the Base of the Robot



Rev: 1A

Date Range: 2507 through 2509

Sample Robot Product Label

Risk	Repair Method
☐ Human Safety - personal injury may occur	□ Repair In Application
☐ Application Safety – application specific	☐ Repair removed from application
damage may occur	
☐ Product Safety - product damage may occur	☐ Repair Center
⋈ No Safety Risk	☐ No Repair Required
Priority	Parts Disposition
☐ Urgent - Immediate Proactive Action	☐ Return Old Parts for Analysis
Required	
☐ Next Visit - Prompt Action Required	☐ Return Old Parts for Repair
□ As Required	☐ Dispose of Old Parts in Appropriate
	Manner
☐ Information Only	
Action	Distribution
☐ Mandatory – All Affected Installations	☐ Brooks Field Service, Support, Repair
□ Recommended	☐ Brooks and OEMs

Uncontrolled Hardcopy



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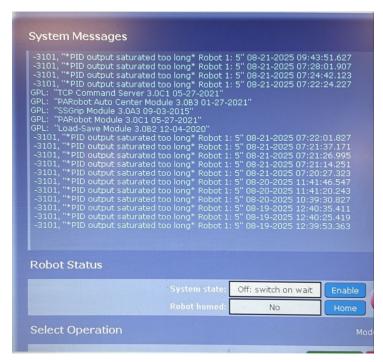
☐ On Failure	☐ Brooks, OEMs, and End Users
☐ No Action Required	☑ Brooks and Specific Groups/OEMs/End
	Users
Reason	Billing
	☐ Retrofit – no charge
Software Issue	☐ Upgrade – billable
☐ Operation Issue	☐ Standard Warranty
☐ Maintenance Issue	\square Other Warranty, see explanation below
\square Information or Documentation	☑ No Billing
☐ Other	

Purpose of this TSB

This TSB notifies customers of error -3101 that may occur with the PreciseFlex 400 robots that were manufactured from July 2025 – September 2025. This notice provides instructions on how to edit the setup parameters to resolve the issue.

Symptoms

While operating the IntelliGuide s23 or v23 gripper on a PreciseFlex 400 robot, high power to the amplifiers may unexpectedly turn off, resulting in the error -3101 "PID output saturation too long" being reported. The -3101 error can be confirmed as the cause by accessing System Messages in the web-based operator interface.





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Additional Warranty Information

N/A

Cause

The problem is traced to incorrect parameters in the 10369 "PID output saturation duration limit, sec" field as shipped from the factory for PreciseFlex 400 robots manufactured during the timeframe of July 2025 – September 2025. Values as shipped from the factory were: 2, 2, 2, 2, 2

Resolution

The issue has been corrected as of September 2025 with the release of new PAC files. The customer can fix the issue by manually updating the System Setup parameters for Data ID#10369 to be: 0.2, 0.2, 0.2, 0.2, 0.

Tools Required

There are no special tools required to perform this update.

Software Required

None. Access to the web-based operator interface is needed.

Procedure

- 1. Access the web-based operator interface for the robot screenshots on following page.
- Navigate to: Setup>System Setup>Parameter Database>Robot: PreciseFlex 400SX (or PreciseFlex 400SXL)>Servo parameters>Compensator>Other and locate data ID "10369 PID output saturation limit, sec"
 - Figure 1 illustrates the problematic factory values of 2, 2, 2, 2
- 3. Edit the values to be: .2, .2, .2, .2, 0
- 4. Select [Set new values]
- 5. Select [Save all to Flash]
 - o Figure 2 illustrates the updated settings.

	End	of	Proced	lure	
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Technical Support Bulletin

-3101 Error, PreciseFlex 400 Revision D Robot

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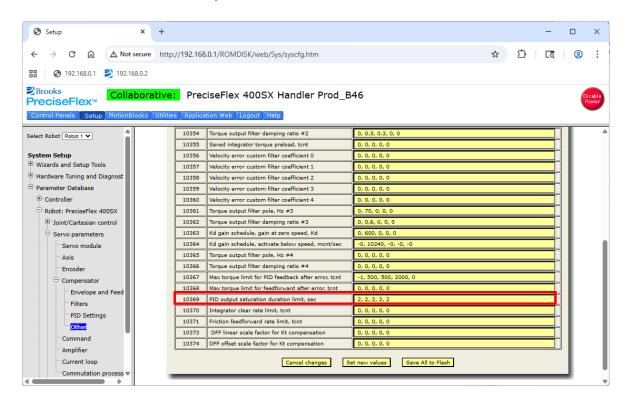


Figure 1: Factory Values for 10369 that cause -3101 Error

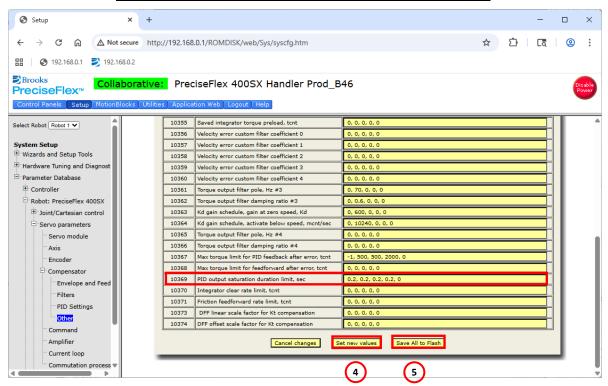


Figure 2: Valid Values for 10369



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If you have any questions, comments, or suggestions regarding this document, please contact Brooks Automation Technical Support at the number or email listed below.

Brooks Location	Contact & Number	
North America - Livermore	Kelvin Chung, Technical	Support_PreciseFlex@brooks.com
	Support Engineer	
	+1 408-224-2838	

Revision History:

Revision	ECO	Date	Action	Author
Α	EC168919	11/20/25	Initial Release	Terese Q. Hibbert